

JULES FRANÇOISE

DESIGNING INTERACTIVE AUDITORY FEEDBACK BY DEMONSTRATION

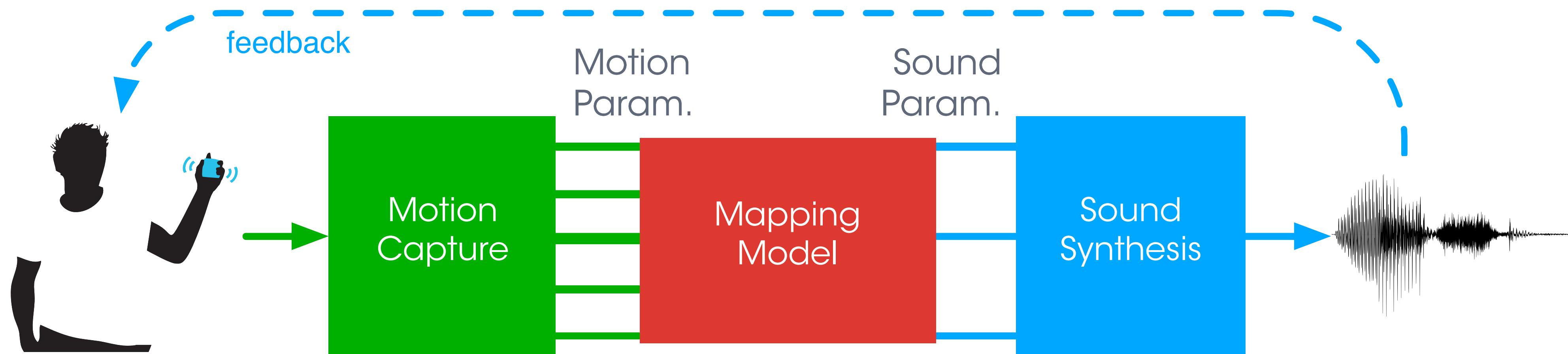
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HAMAC @ Ircam — 2018/07/09

AUDITORY FEEDBACK SYSTEMS



real-time continuous and multidimensional interaction

Introduction

APPLICATIONS

Music & Performing Arts

Installations & Gaming

Movement Learning



sound = explicit goal

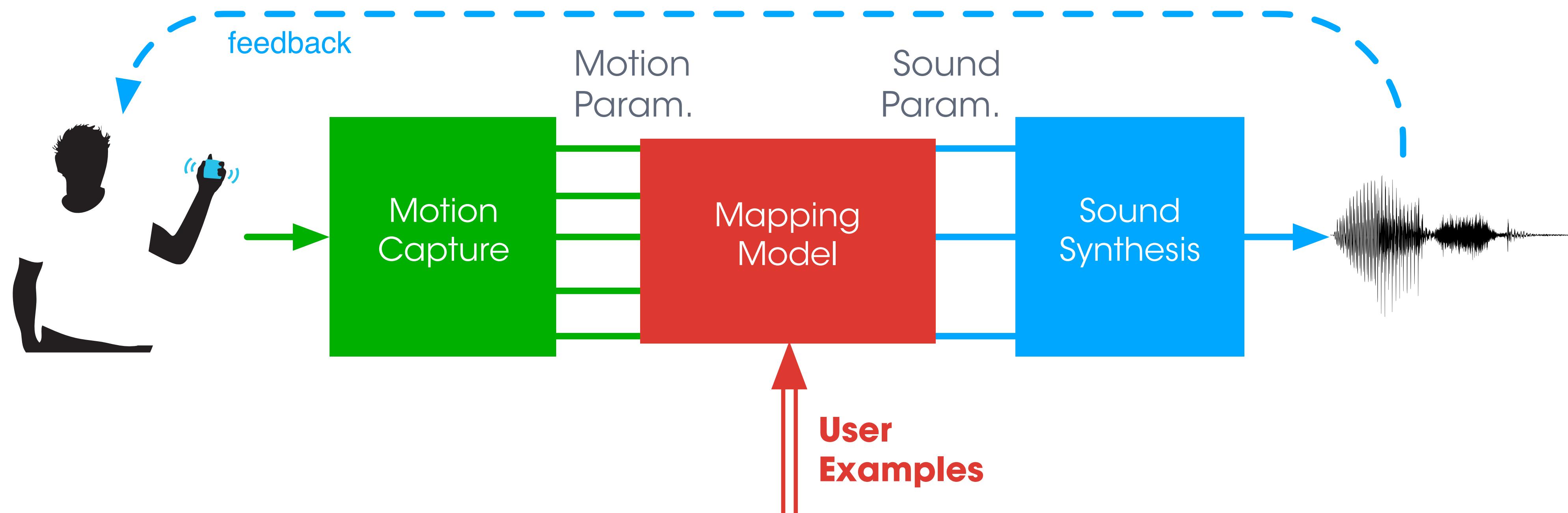
sound = implicit support to movement

=> need for personalization / user adaptation

MOTION-SOUND MAPPING BY DEMONSTRATION

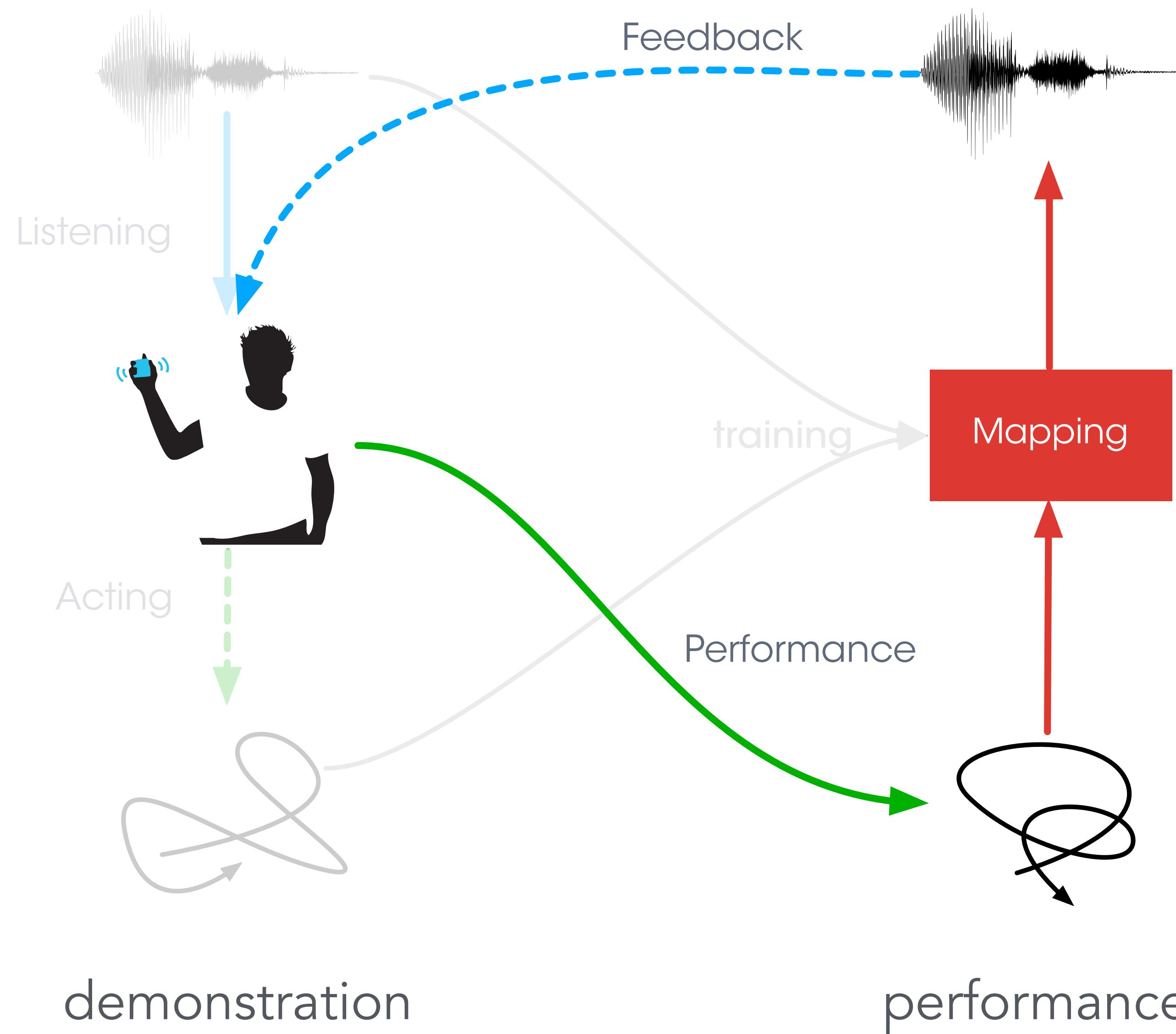
MOTION-SOUND MAPPING

Implicit Mapping with Machine Learning

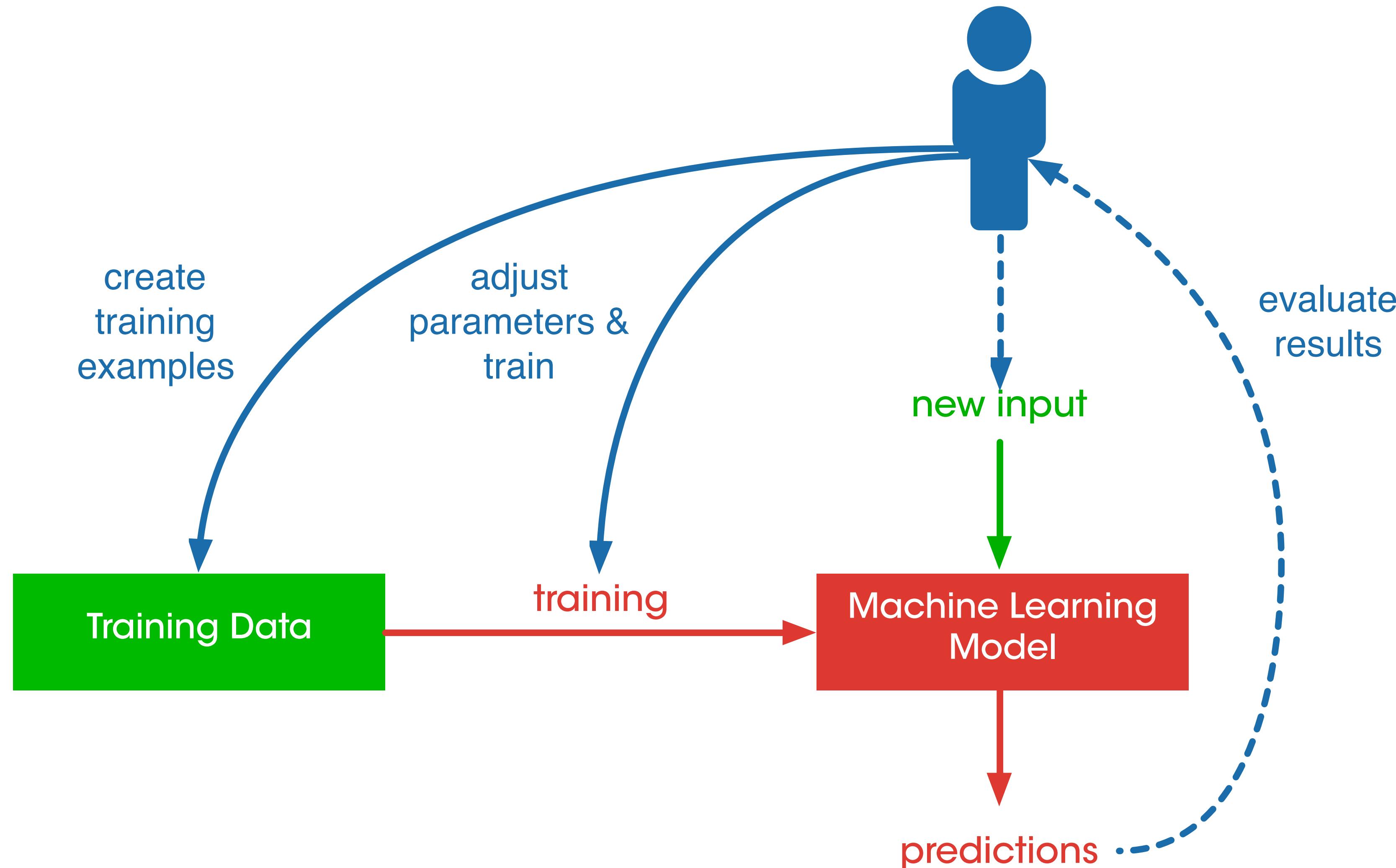


Mapping by Demonstration

PRINCIPLE



INTERACTIVE MACHINE LEARNING



MODELS

Temporal
Instantaneous

Recognition

Gaussian Mixture Models

gmm

Generation

Gaussian Mixture Regression

gmr

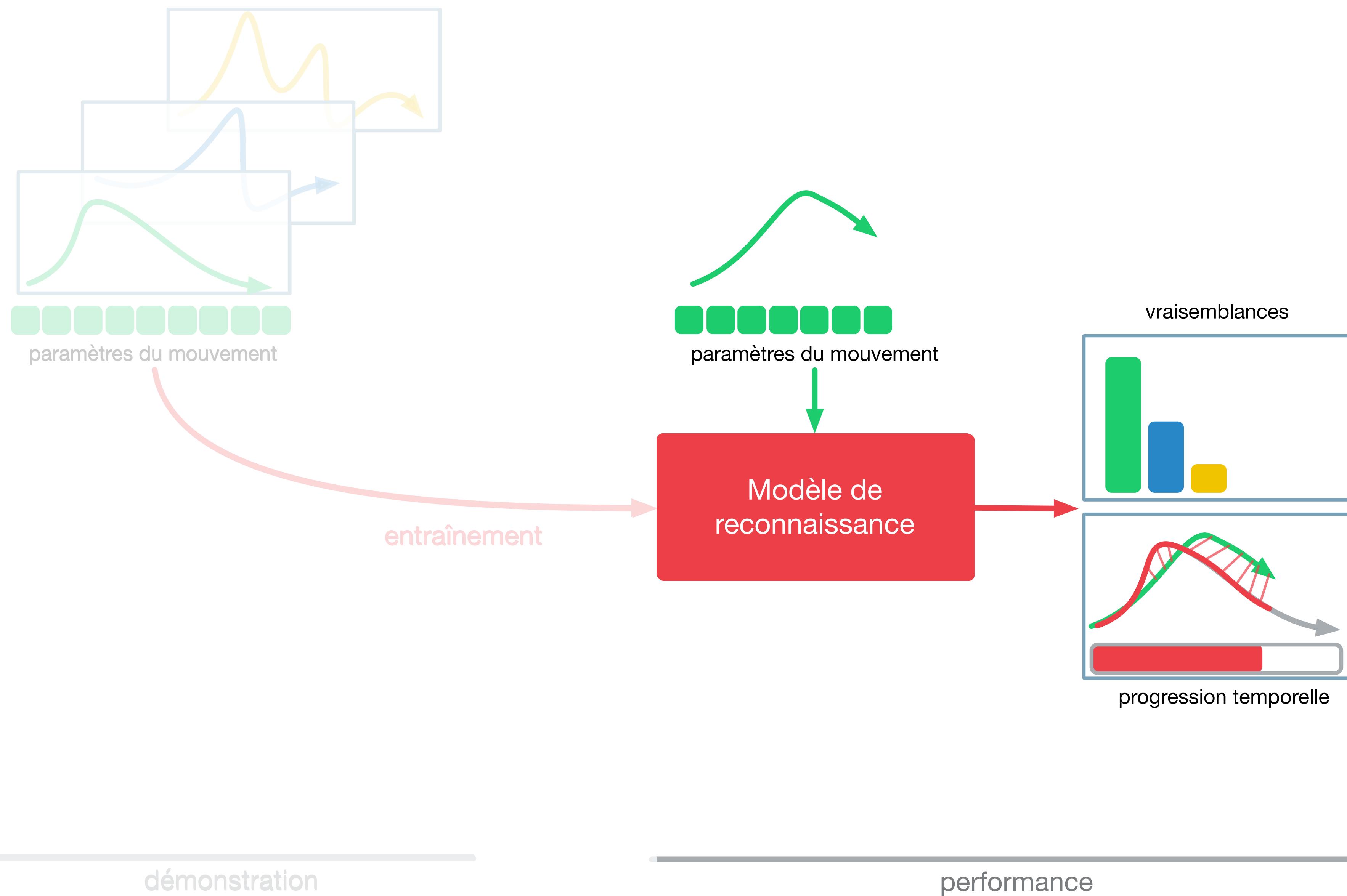
**Hierarchical
Hidden Markov Models**

hhmm

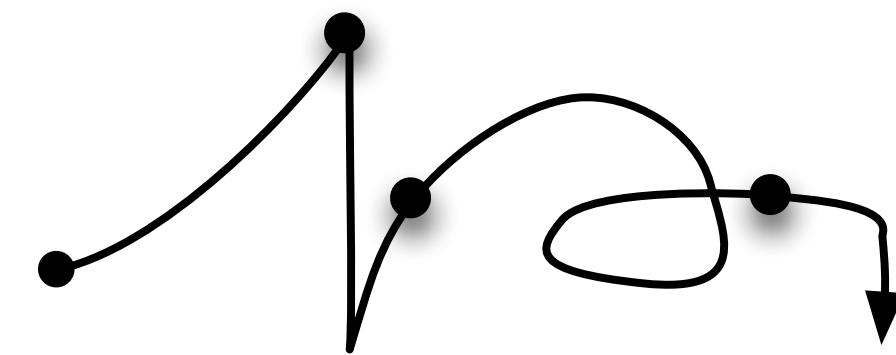
**Hierarchical
Hidden Markov Regression**

hhmr

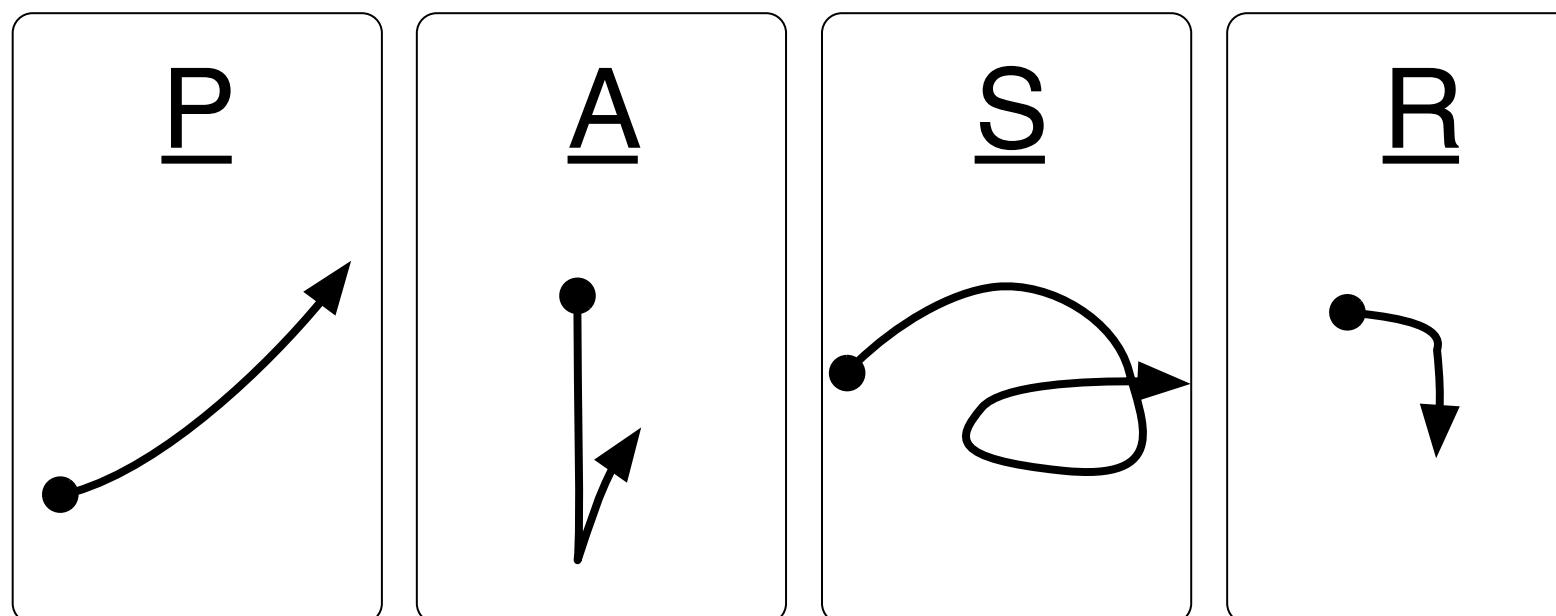
RECOGNITION MODELS



HIERARCHICAL MARKOV MODELS



Example gesture



PASR decomposition

4 Phases:

Preparation

(P) > anticipation gesture

Attack

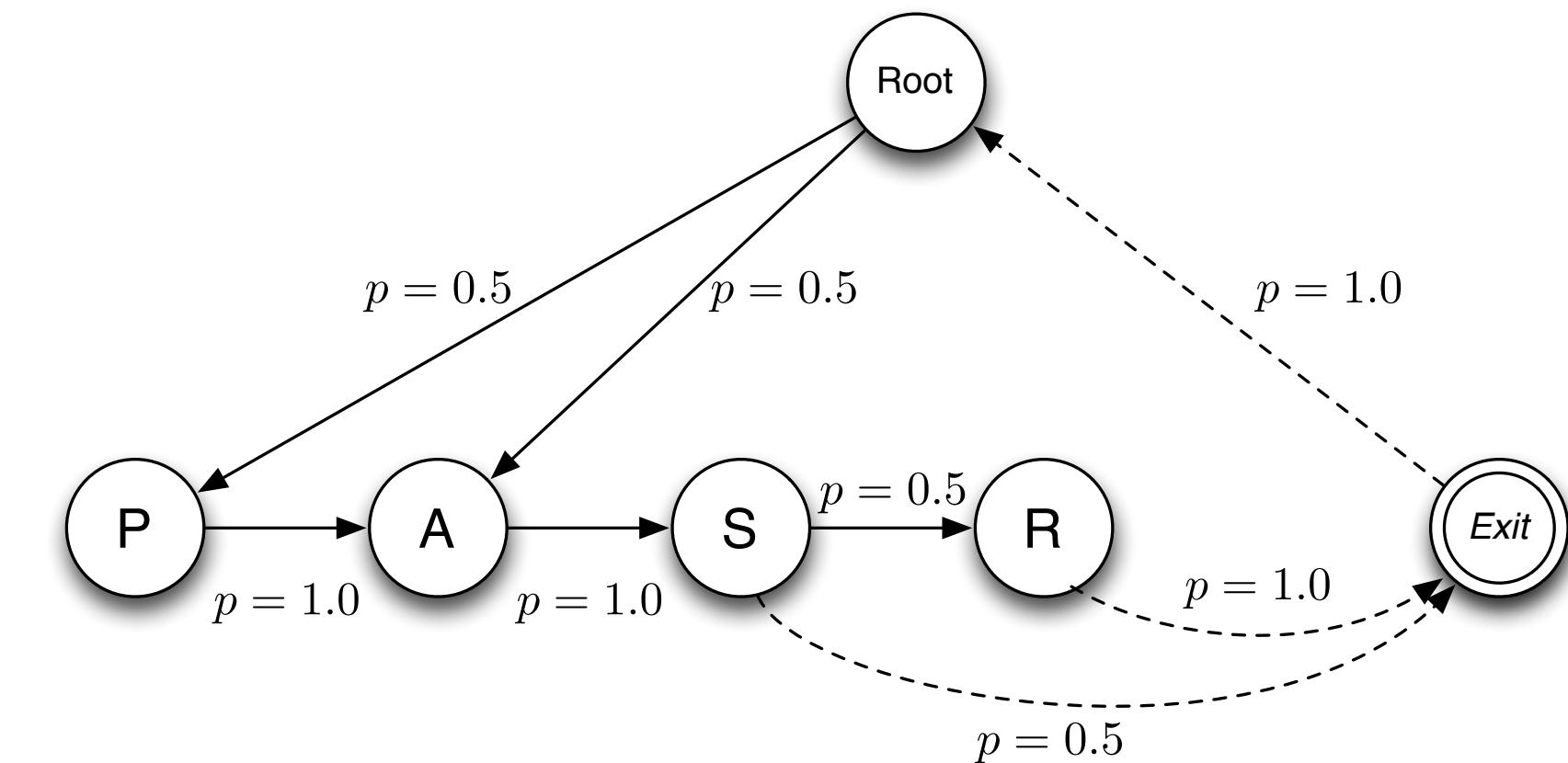
(A)

Sustain

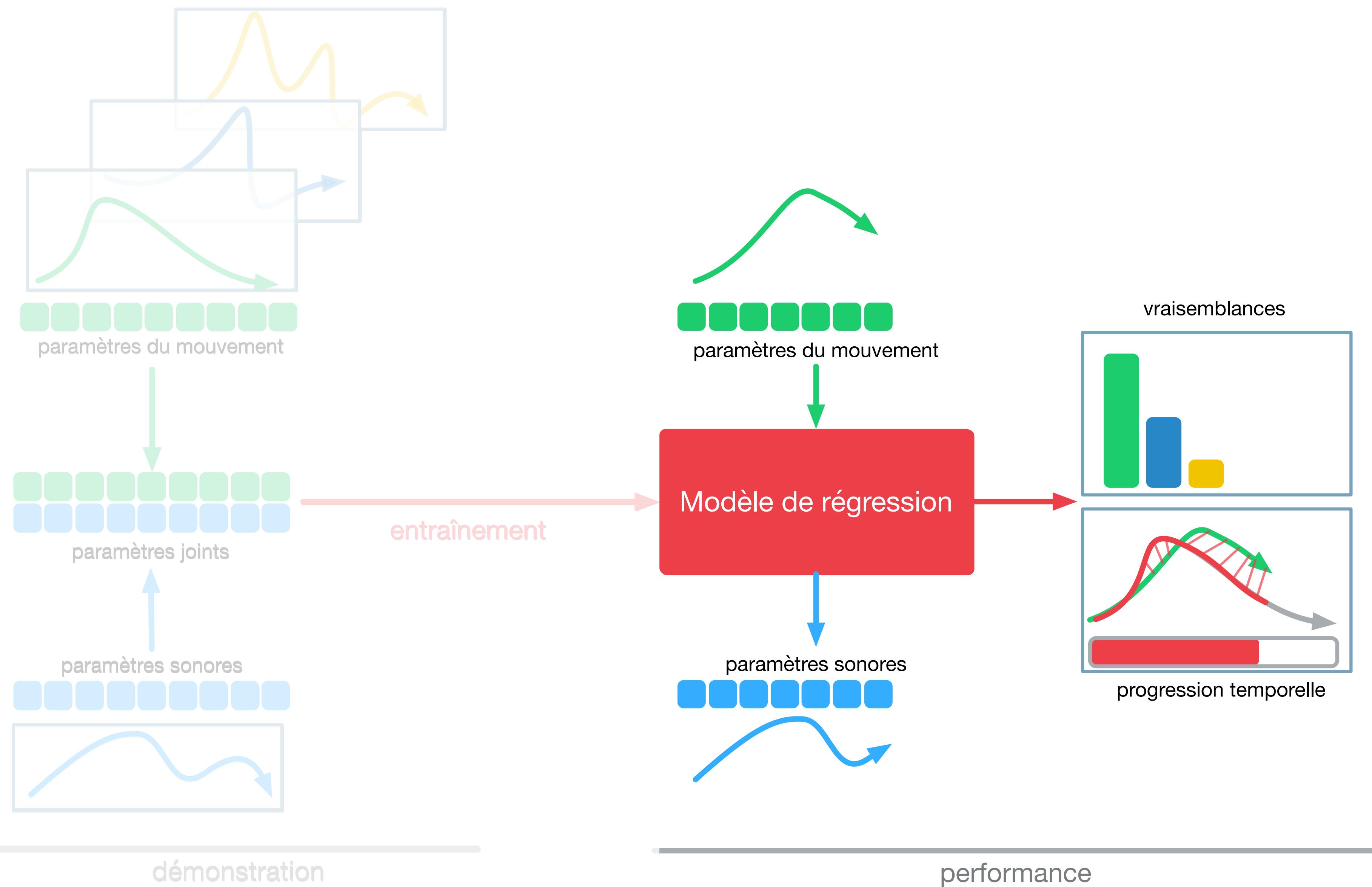
(S)

Release

(R) > retraction gesture



GENERATIVE MODELS



DISCUSSION

DESIGNING WITH MACHINE LEARNING

- **Advantages**
 - No need for a formal (mathematical) description of the problem
 - Design using bodily knowledge
 - Specification of (possibly complex) target gestures for sonification
 - Individualized adaptation
- **But...**
 - How do we make it work?

DESIGN PROCESS

- **Process**
 - The user imagines a vocabulary of gestures (+ sounds)
 - The user records demonstrations
 - The ML algorithm learns the mapping/classifier
 - It does **not** work.
- **Reasons for Failure**
 - *Technical factors*
 - Appropriate choice of sensor, features, model, and parameters
 - High-quality examples
 - *Cognitive and sensori-motor factors*
 - Gesture design + Execution

AN ITERATIVE PROCESS

- **Co-adaptive perspective (partnership?)**
 - The human and the machine iteratively learn from each other
 - The user is responsible for most of the adaptation
 - MbD as a reflective tool
- **How to make it work?**
 - Improve the transparency
 - Support practice & exploration

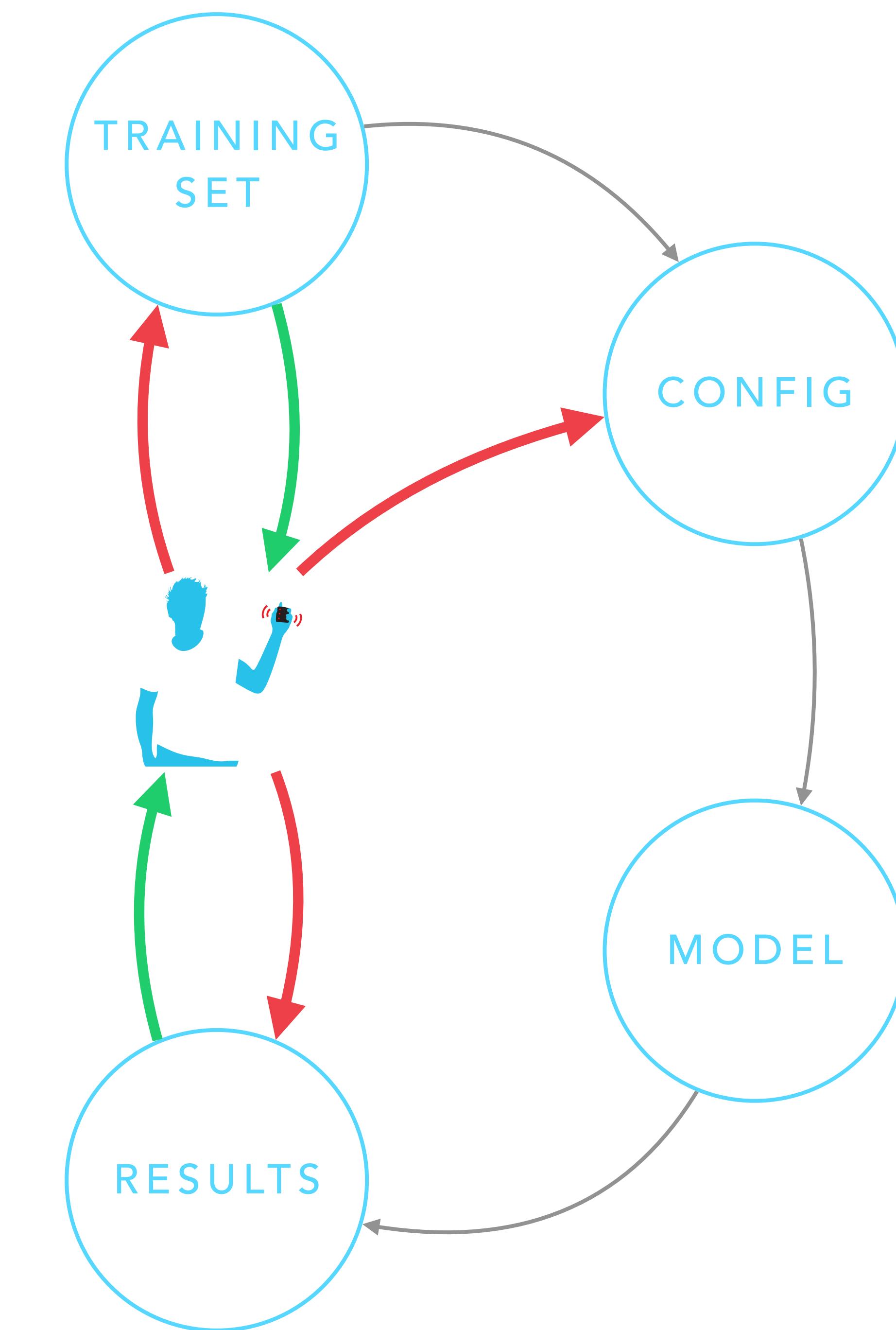
VISUALIZING PROBABILISTIC MODELS

w. Fred Vernier, Antonin Cheymol

INTERACTIVE MACHINE LEARNING

1. Create Training Examples
 1. Feedback on Training Set
2. Adjust Parameters
3. Provide New Input
 2. Feedback on results {during interaction}

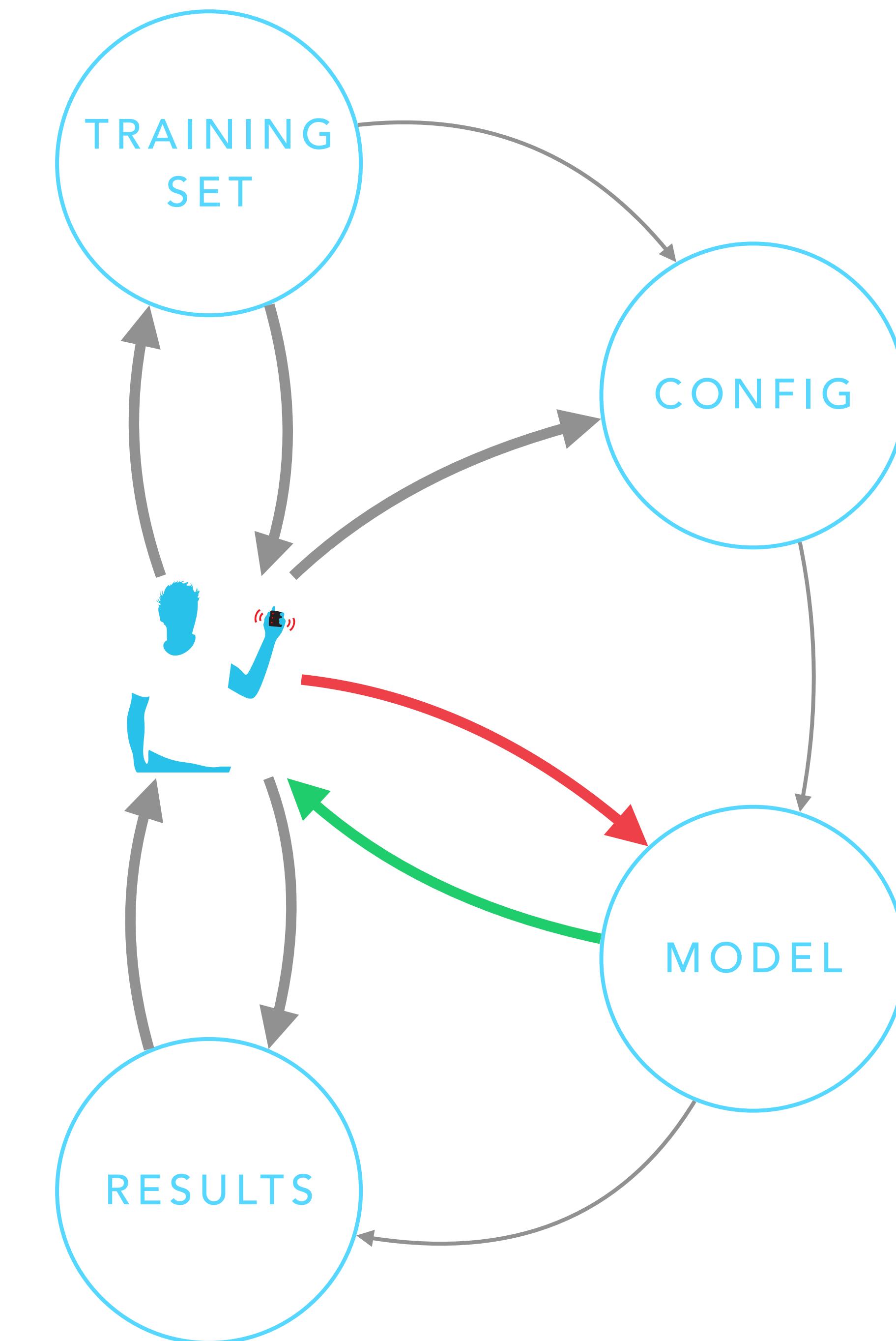
EnsembleMatrix, ModelTracker, ...



INTERACTIVE MACHINE LEARNING

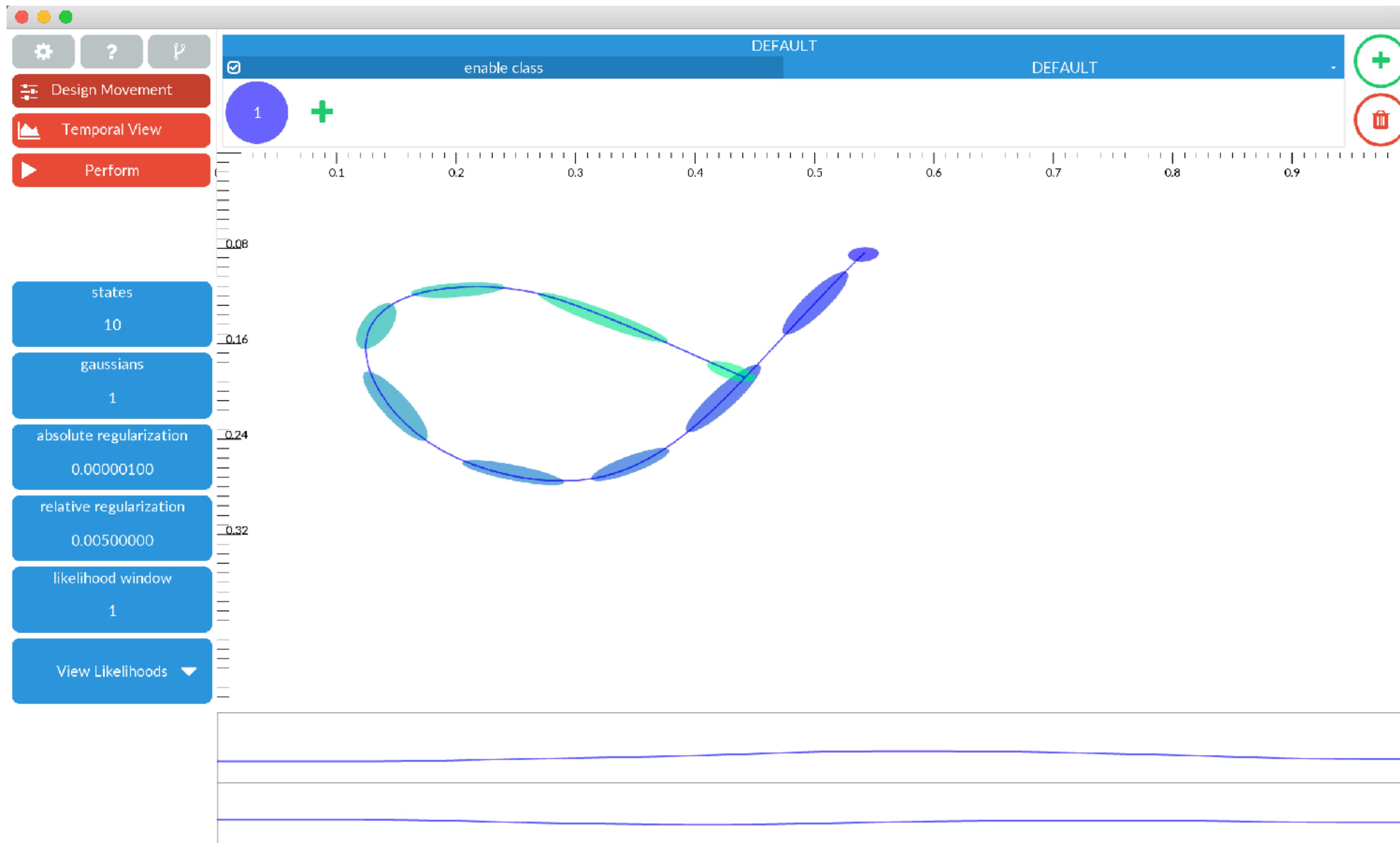
1. Create Training Examples
 1. Feedback on Training Set
2. Adjust Parameters

Visualize {inside} models
=> Manipulate models from visuals
3. Provide New Input
 2. Feedback on results {during interaction}



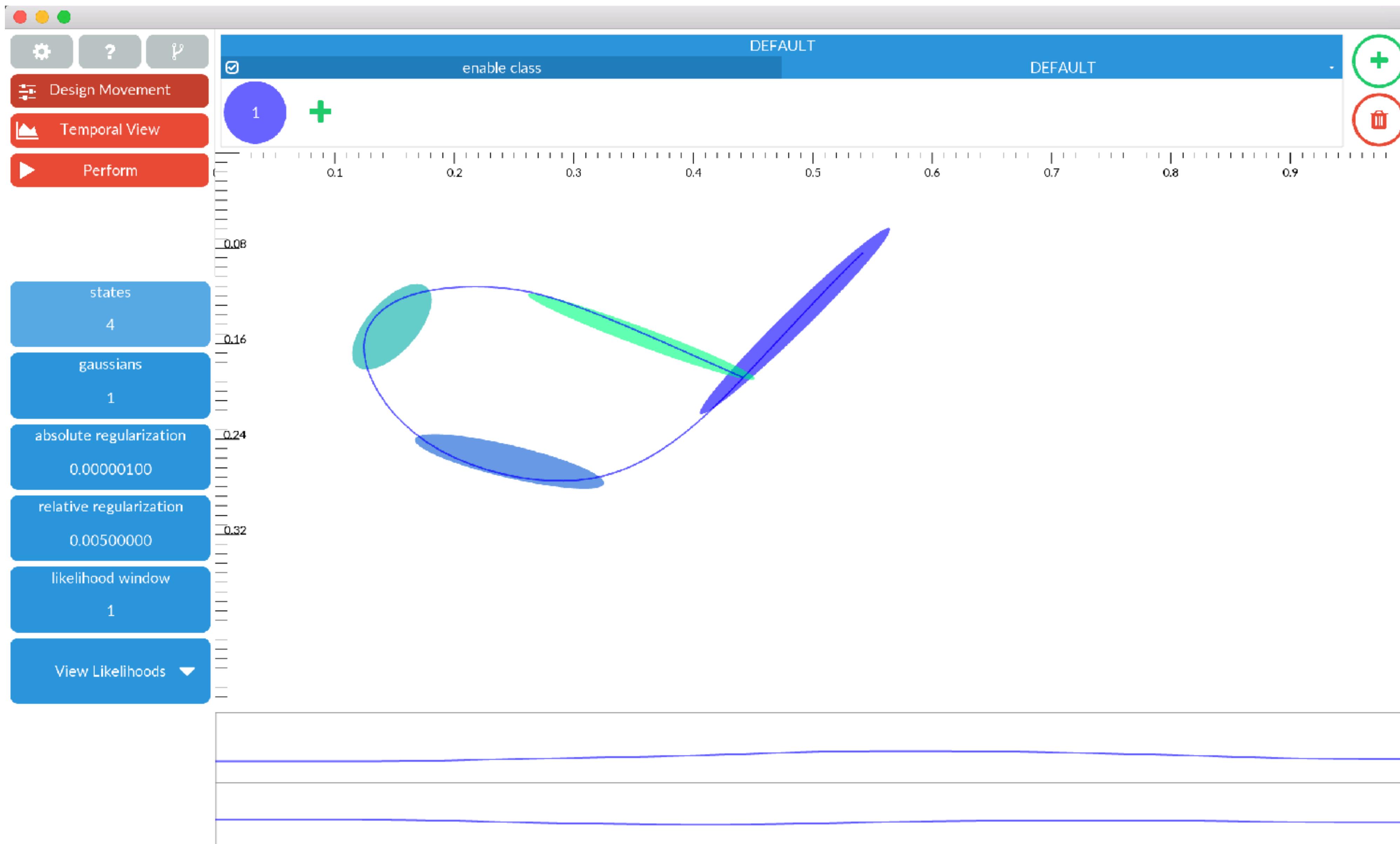
Visualizing probabilistic models

GAUSSBOX : HMM VISUALISATION



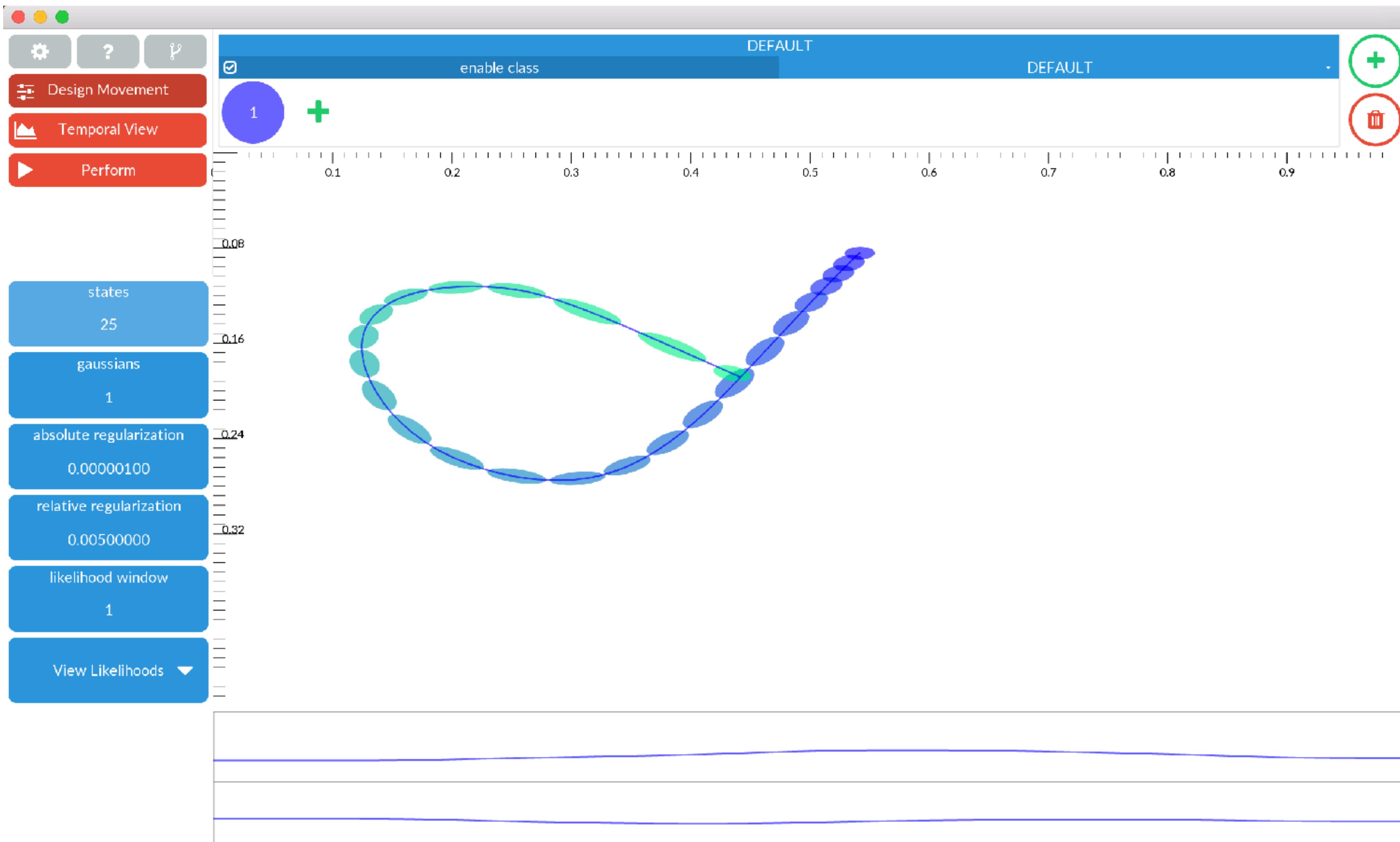
Visualizing probabilistic models

GAUSSBOX : HMM VISUALISATION



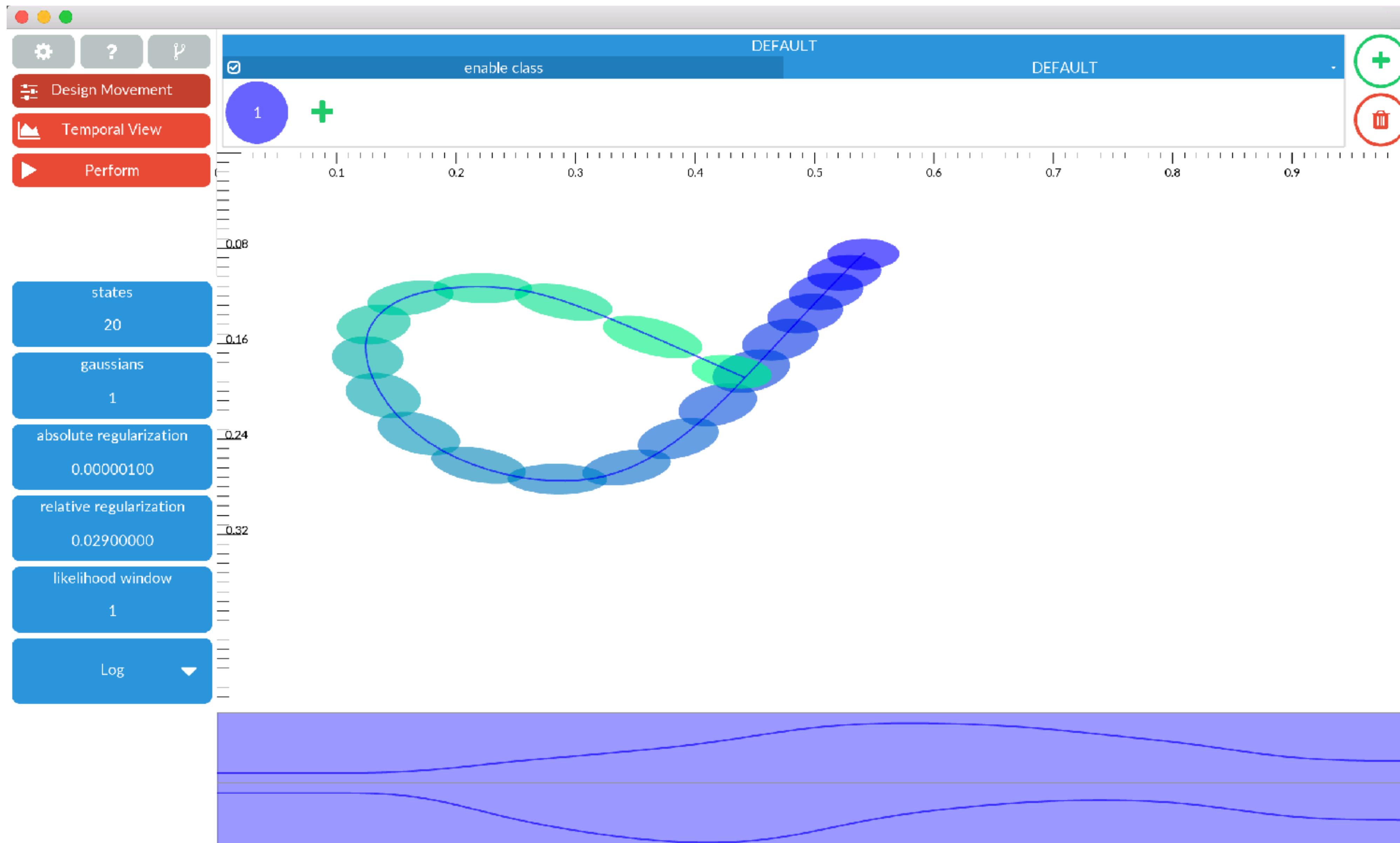
Visualizing probabilistic models

GAUSSBOX : HMM VISUALISATION



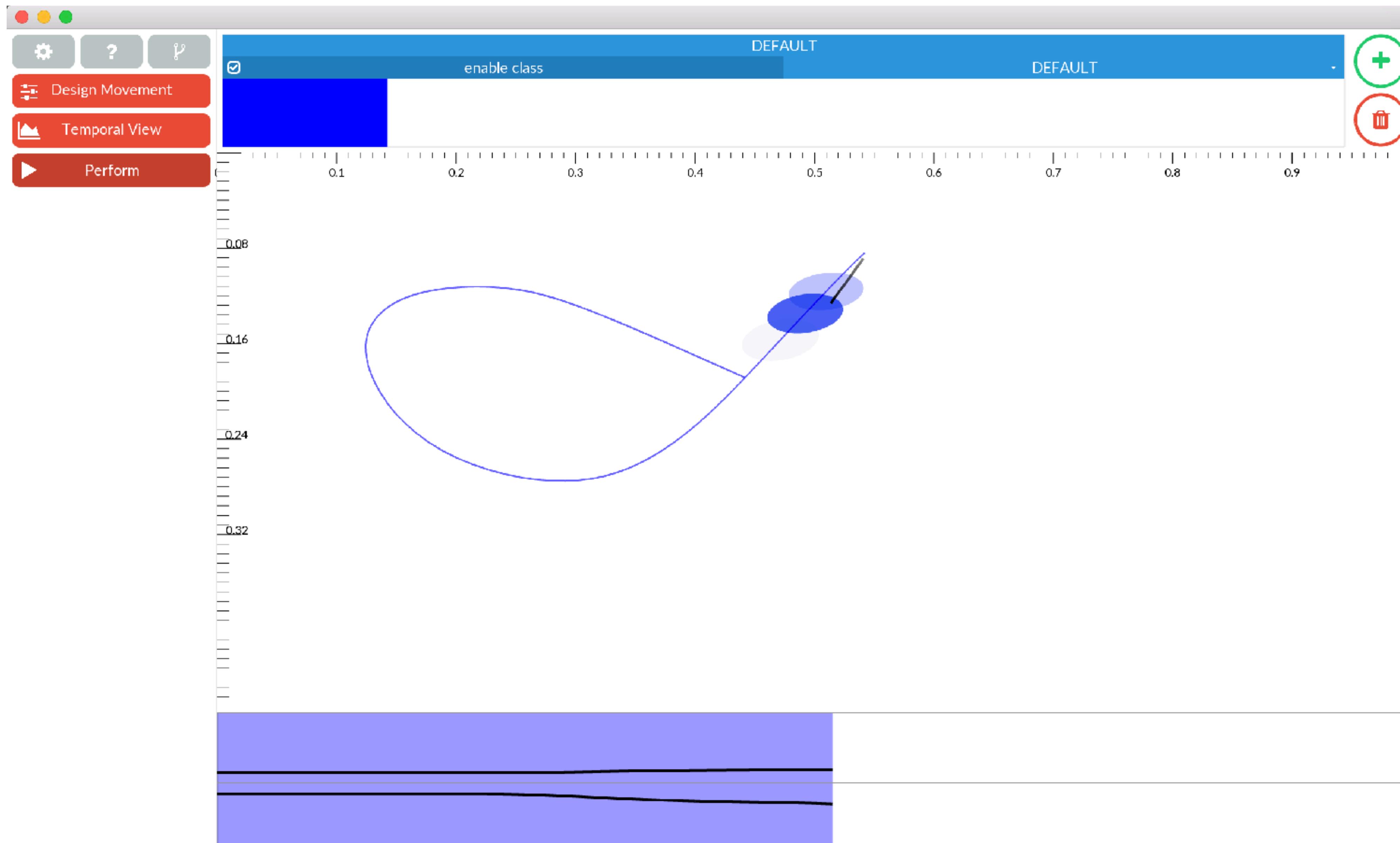
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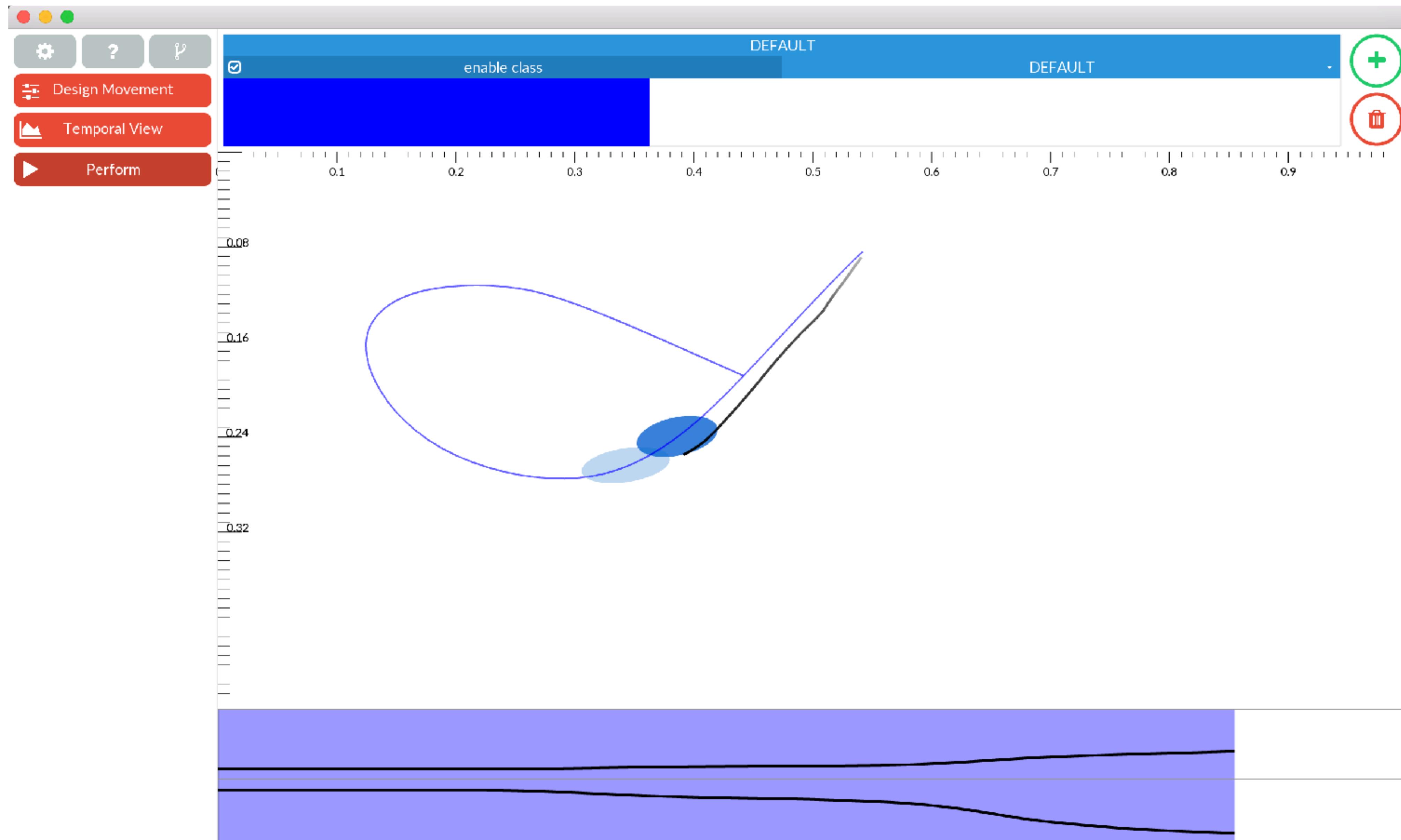
Visualizing probabilistic models

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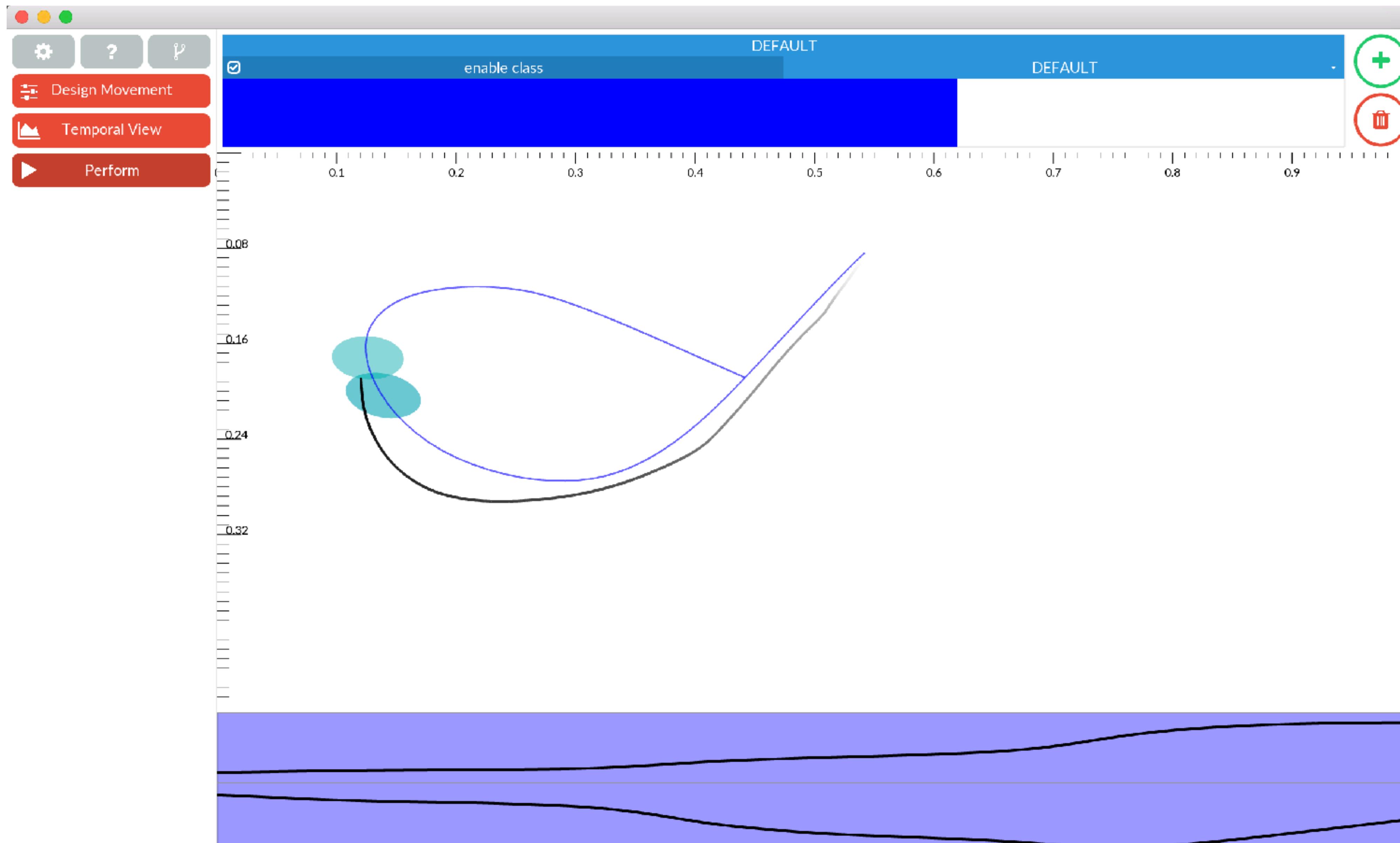


Visualizing probabilistic models

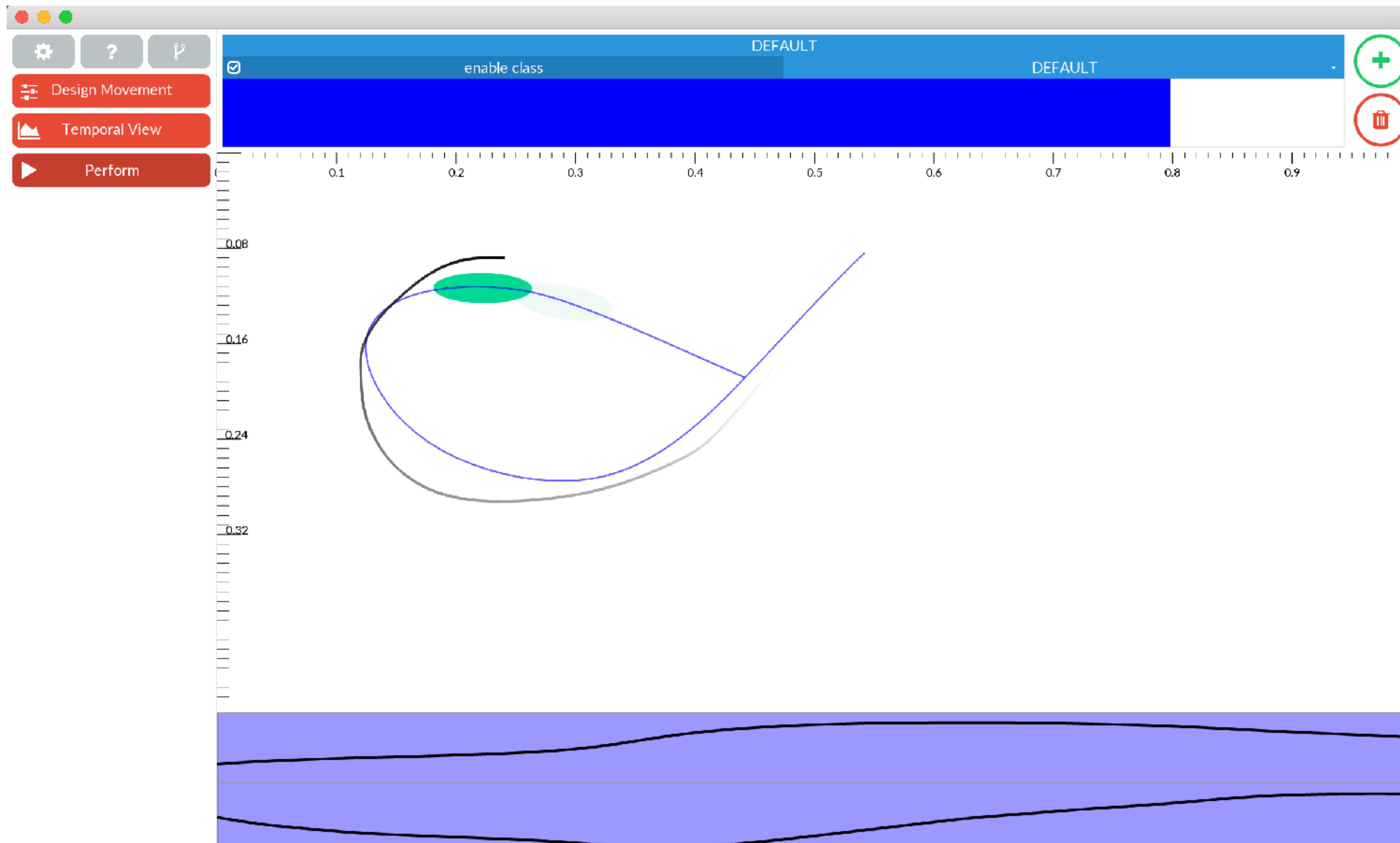
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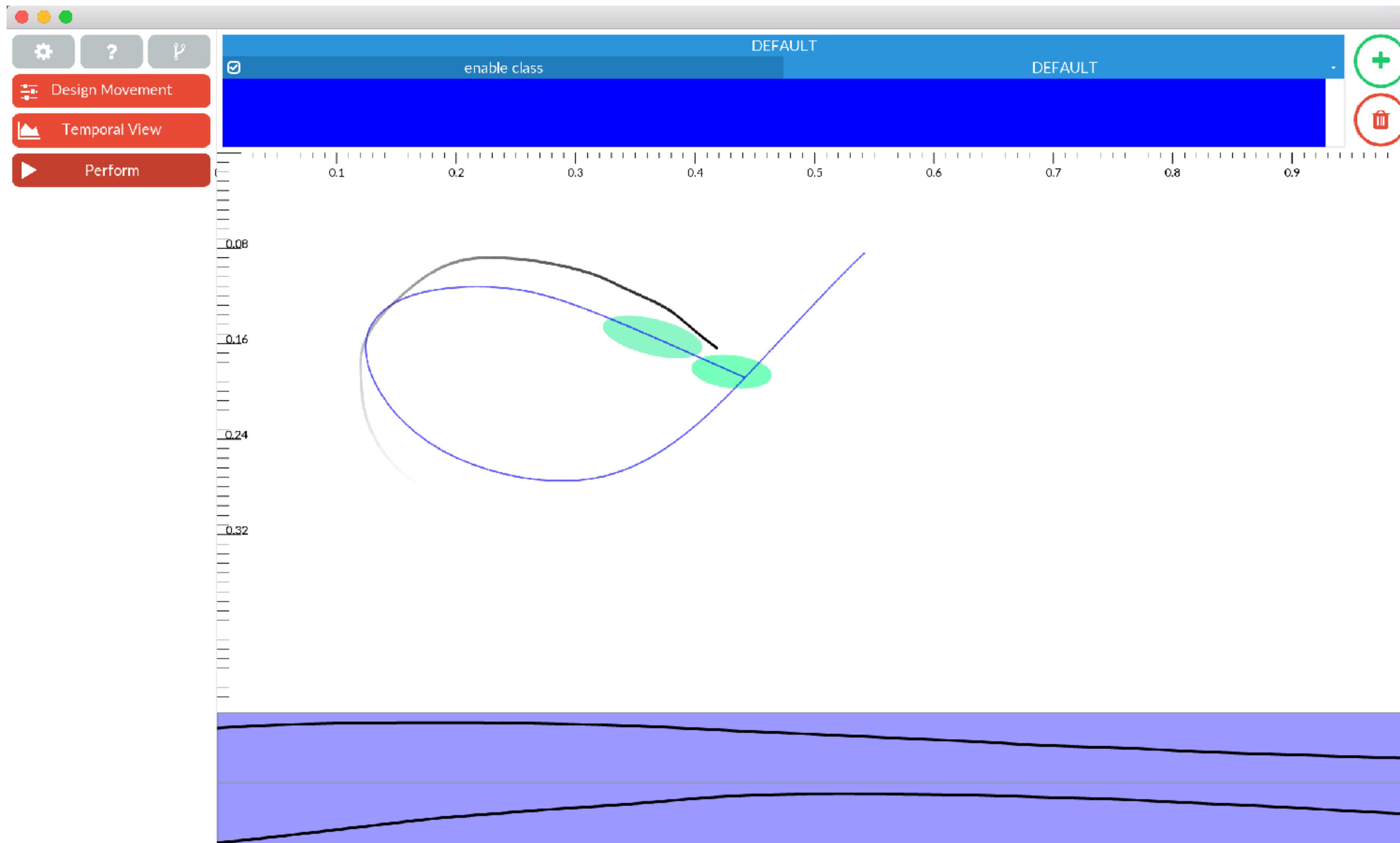


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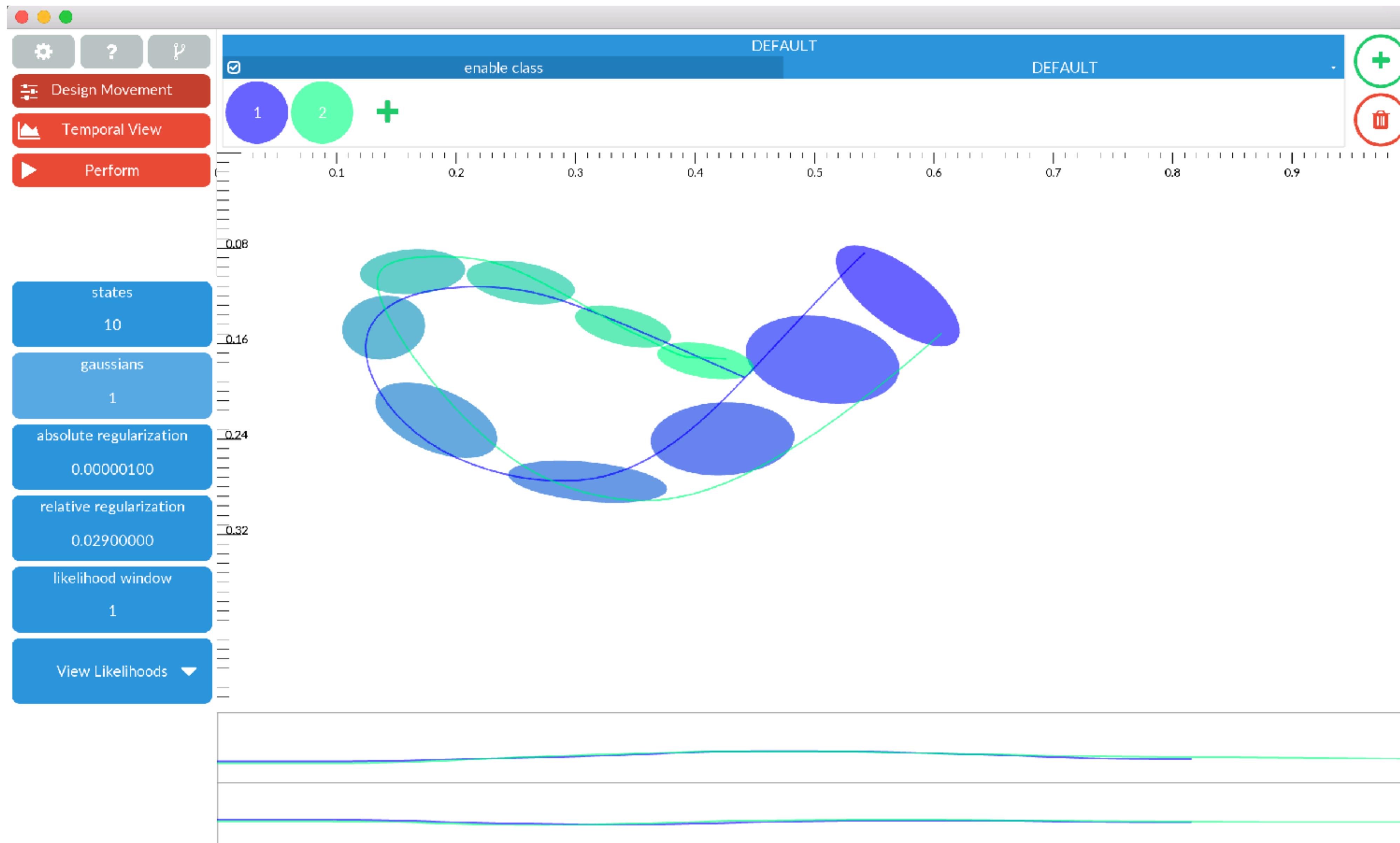
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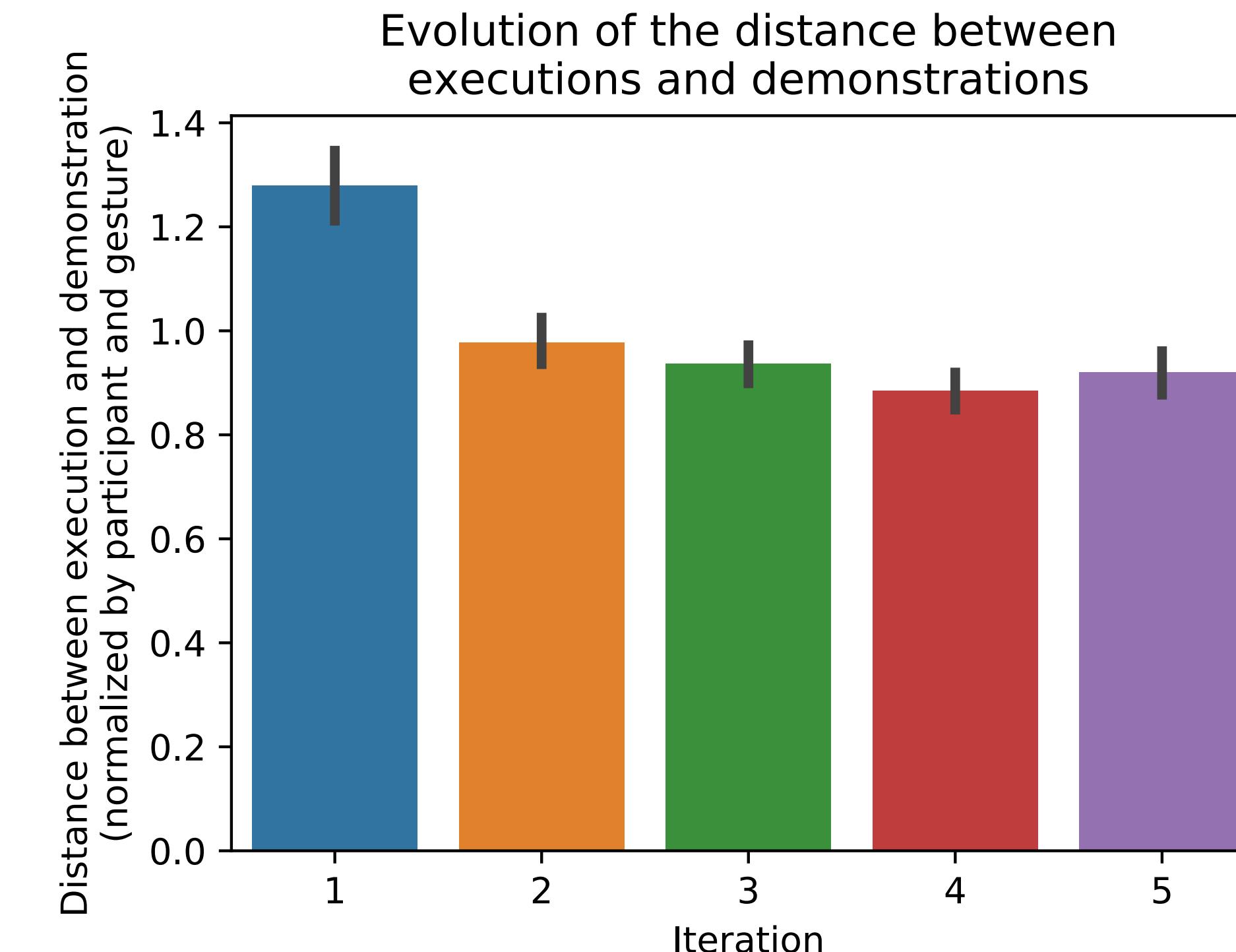
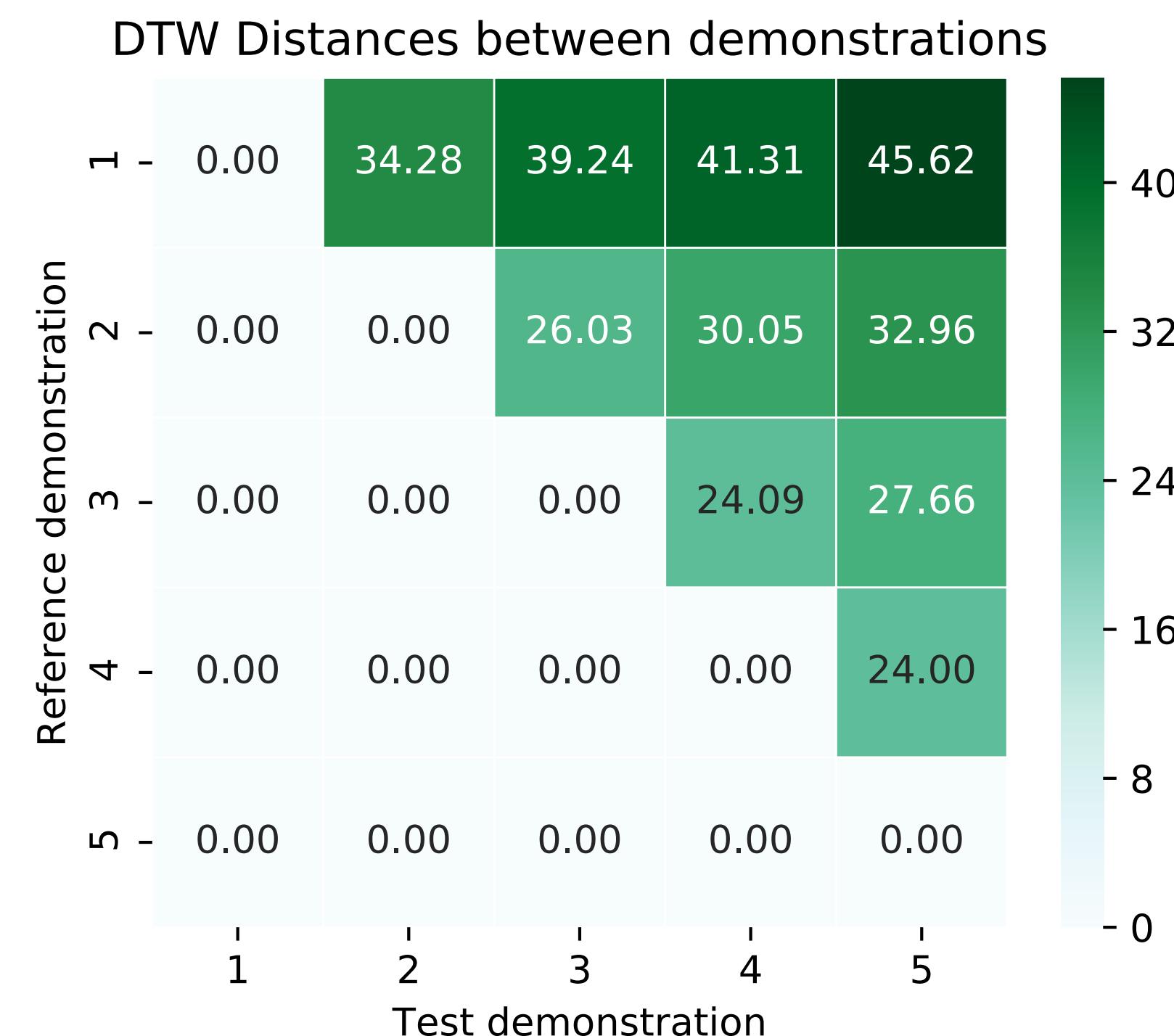


EXPLORING/PRACTICING

Discussion

A LEARNING PROCESS

- User study: sonification using vocalisation
- Users adapt their gesture design by iterating over demonstration & performance
- The gesture design converges along iterations
- The consistency of the execution improves over time

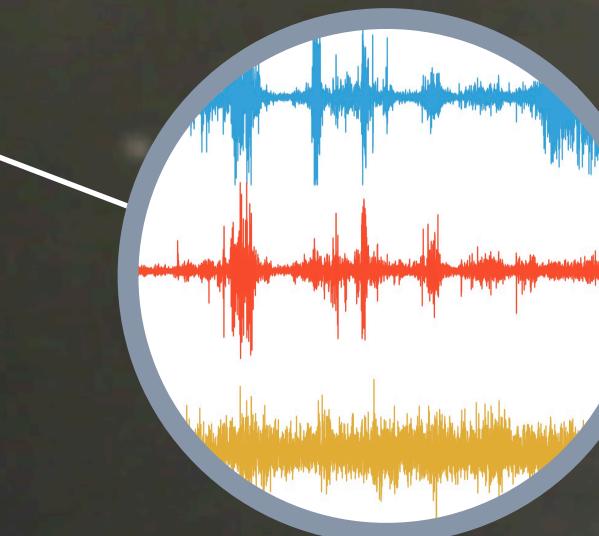


still, moving

(Interactive Sound Installation)

w. Sarah Fdili Alaoui, Yves Candau

Myo (Electromyogram)







Towards live-coding

w. Sarah Fdili Alaoui, Yves Candau, Lucie Van Nieuwenhuyze



CONCLUSIONS

- **Mapping by Demonstration**
 - Tool for personalising motion-sound interactions
 - From *designing by example* to *designing through practice*
- **How to support the design process**
 - Help users understand the models?
 - Support exploration & practice
 -

THANK YOU

... and thanks to many collaborators :

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